

# Integrating geodesic flows : finding supergravity cosmologies and black holes

Wissam Chemissany  
U of L, Alberta, Canada

Based on: W.C, P. Fré, Alexander Sorin, **arXiv:0904.0801**  
W. C, M. Trigiante, T. Van Riet, Jan.R., **arXiv:0903.2777**  
W. C, P. Fré, A. Sorin, M. Trigiante, T. Van Riet, Jan.Rosseel, **arXiv:1007.3209**  
W.C, M. Walton, **to appear**

ERE2010, 06/09/2010

# Outline

1. Introduction
2. Branes as geodesics on moduli space
3. The geodesic equations in Lax pair form
4. Initial conditions
5. The simplest example :  $S \ell(2, \mathbb{R})$
6. A universal integration algorithm
7. Liouville Integrability
8. Conclusion and Outlook

# Introduction : Goals

- ▶ **Main goal** : finding  $p$ -brane type solutions of supergravity theories in an algorithmic manner. We consider both time-like branes, as well as space-like branes.
- ▶ **Strategy** : use the fact that, in case symmetry is present, the branes are described by geodesic motion on a certain moduli space (after performing a certain dimensional reduction).
- ▶ In case the moduli space is a *symmetric space*, the geodesic equations that describe *both* time-like and space-like branes can be written in a specific form : the Lax pair form.
- ▶ This rewriting establishes integrability. The explicit integration can moreover be done in an algorithmic manner.
- ▶ In this way, one can find (after oxidation) cosmological solutions of SUGRA, as well as e.g. black hole solutions (both BPS and non-BPS) without relying on supersymmetry arguments.

# Introduction : Goals

- ▶ **Main goal** : finding  $p$ -brane type solutions of supergravity theories in an algorithmic manner. We consider both time-like branes, as well as space-like branes.
- ▶ **Strategy** : use the fact that, in case symmetry is present, the branes are described by geodesic motion on a certain moduli space (after performing a certain dimensional reduction).
- ▶ In case the moduli space is a *symmetric space*, the geodesic equations that describe *both* time-like and space-like branes can be written in a specific form : the Lax pair form.
- ▶ This rewriting establishes integrability. The explicit integration can moreover be done in an algorithmic manner.
- ▶ In this way, one can find (after oxidation) cosmological solutions of SUGRA, as well as e.g. black hole solutions (both BPS and non-BPS) without relying on supersymmetry arguments.

# Introduction : Goals

- ▶ **Main goal** : finding  $p$ -brane type solutions of supergravity theories in an algorithmic manner. We consider both time-like branes, as well as space-like branes.
- ▶ **Strategy** : use the fact that, in case symmetry is present, the branes are described by geodesic motion on a certain moduli space (after performing a certain dimensional reduction).
- ▶ In case the moduli space is a *symmetric space*, the geodesic equations that describe *both* time-like and space-like branes can be written in a specific form : the Lax pair form.
- ▶ This rewriting establishes integrability. The explicit integration can moreover be done in an algorithmic manner.
- ▶ In this way, one can find (after oxidation) cosmological solutions of SUGRA, as well as e.g. black hole solutions (both BPS and non-BPS) without relying on supersymmetry arguments.

# Introduction : Goals

- ▶ **Main goal** : finding  $p$ -brane type solutions of supergravity theories in an algorithmic manner. We consider both time-like branes, as well as space-like branes.
- ▶ **Strategy** : use the fact that, in case symmetry is present, the branes are described by geodesic motion on a certain moduli space (after performing a certain dimensional reduction).
- ▶ In case the moduli space is a *symmetric space*, the geodesic equations that describe *both* time-like and space-like branes can be written in a specific form : the Lax pair form.
- ▶ This rewriting establishes integrability. The explicit integration can moreover be done in an algorithmic manner.
- ▶ In this way, one can find (after oxidation) cosmological solutions of SUGRA, as well as e.g. black hole solutions (both BPS and non-BPS) without relying on supersymmetry arguments.

# Introduction : Goals

- ▶ **Main goal** : finding  $p$ -brane type solutions of supergravity theories in an algorithmic manner. We consider both time-like branes, as well as space-like branes.
- ▶ **Strategy** : use the fact that, in case symmetry is present, the branes are described by geodesic motion on a certain moduli space (after performing a certain dimensional reduction).
- ▶ In case the moduli space is a *symmetric space*, the geodesic equations that describe *both* time-like and space-like branes can be written in a specific form : the Lax pair form.
- ▶ This rewriting establishes integrability. The explicit integration can moreover be done in an algorithmic manner.
- ▶ In this way, one can find (after oxidation) cosmological solutions of SUGRA, as well as e.g. black hole solutions (both BPS and non-BPS) without relying on supersymmetry arguments.

# Branes as geodesics on moduli space

- ▶  $p$ -brane solutions in  $d$  dimensions are charged electrically under  $A_{p+1}$  or magnetically under  $A_{d-p-3}$ .

$$ds_d^2 = e^{2A(r)} \eta_{\mu\nu} dx^\mu dx^\nu + e^{2B(r)} (dr^2 + r^2 d\Omega_{d-p-2}^2) \quad (\text{time - like}),$$

$$ds_d^2 = e^{2A(t)} \delta_{\mu\nu} dx^\mu dx^\nu + e^{2B(t)} (-dt^2 + r^2 d\Sigma_{d-p-2}^2) \quad (\text{space - like})$$

- ▶ Transversal symmetries :  $SO(d - p - 1)$  or  $SO(d - p - 2, 1)$
- ▶ Worldvolume symmetries contain an  $\mathbb{R}^{p+1}$  subgroup of translations  $\longrightarrow$  matter fields are translation invariant.
- ▶ For the purpose of finding solutions : effectively dimensionally reduce the solutions over its worldvolume :

$p$ -brane in  $d$  dim.  $\longrightarrow$   $-1$ -brane in  $D = d - p - 1$  dim.

$$S = \int d^D x \sqrt{|g|} \left\{ R - \frac{1}{2} G_{ij}(\phi) \partial\phi^i \partial\phi^j \right\}.$$



# Branes as geodesics on moduli space

- ▶  $p$ -brane solutions in  $d$  dimensions are charged electrically under  $A_{p+1}$  or magnetically under  $A_{d-p-3}$ .

$$ds_d^2 = e^{2A(r)} \eta_{\mu\nu} dx^\mu dx^\nu + e^{2B(r)} (dr^2 + r^2 d\Omega_{d-p-2}^2) \quad (\text{time-like}),$$

$$ds_d^2 = e^{2A(t)} \delta_{\mu\nu} dx^\mu dx^\nu + e^{2B(t)} (-dt^2 + r^2 d\Sigma_{d-p-2}^2) \quad (\text{space-like})$$

- ▶ Transversal symmetries :  $\text{SO}(d-p-1)$  or  $\text{SO}(d-p-2, 1)$
- ▶ Worldvolume symmetries contain an  $\mathbb{R}^{p+1}$  subgroup of translations  $\longrightarrow$  matter fields are translation invariant.
- ▶ For the purpose of finding solutions : effectively dimensionally reduce the solutions over its worldvolume :

$p$ -brane in  $d$  dim.  $\longrightarrow$   $-1$ -brane in  $D = d - p - 1$  dim.

$$S = \int d^D x \sqrt{|g|} \left\{ R - \frac{1}{2} G_{ij}(\phi) \partial\phi^i \partial\phi^j \right\}.$$

# Branes as geodesics on moduli space

- ▶  $p$ -brane solutions in  $d$  dimensions are charged electrically under  $A_{p+1}$  or magnetically under  $A_{d-p-3}$ .

$$ds_d^2 = e^{2A(r)} \eta_{\mu\nu} dx^\mu dx^\nu + e^{2B(r)} (dr^2 + r^2 d\Omega_{d-p-2}^2) \quad (\text{time-like}),$$

$$ds_d^2 = e^{2A(t)} \delta_{\mu\nu} dx^\mu dx^\nu + e^{2B(t)} (-dt^2 + r^2 d\Sigma_{d-p-2}^2) \quad (\text{space-like})$$

- ▶ Transversal symmetries :  $\text{SO}(d-p-1)$  or  $\text{SO}(d-p-2, 1)$
- ▶ Worldvolume symmetries contain an  $\mathbb{R}^{p+1}$  subgroup of translations  $\rightarrow$  matter fields are translation invariant.
- ▶ For the purpose of finding solutions : effectively dimensionally reduce the solutions over its worldvolume :

$p$ -brane in  $d$  dim.  $\rightarrow$   $-1$ -brane in  $D = d - p - 1$  dim.

$$S = \int d^D x \sqrt{|g|} \left\{ R - \frac{1}{2} G_{ij}(\phi) \partial\phi^i \partial\phi^j \right\}.$$

# Branes as geodesics on moduli space

- ▶  $p$ -brane solutions in  $d$  dimensions are charged electrically under  $A_{p+1}$  or magnetically under  $A_{d-p-3}$ .

$$ds_d^2 = e^{2A(r)} \eta_{\mu\nu} dx^\mu dx^\nu + e^{2B(r)} (dr^2 + r^2 d\Omega_{d-p-2}^2) \quad (\text{time-like}),$$

$$ds_d^2 = e^{2A(t)} \delta_{\mu\nu} dx^\mu dx^\nu + e^{2B(t)} (-dt^2 + r^2 d\Sigma_{d-p-2}^2) \quad (\text{space-like})$$

- ▶ Transversal symmetries :  $\text{SO}(d-p-1)$  or  $\text{SO}(d-p-2, 1)$
- ▶ Worldvolume symmetries contain an  $\mathbb{R}^{p+1}$  subgroup of translations  $\longrightarrow$  matter fields are translation invariant.
- ▶ For the purpose of finding solutions : effectively dimensionally reduce the solutions over its worldvolume :

$p$ -brane in  $d$  dim.  $\longrightarrow$   $-1$ -brane in  $D = d - p - 1$  dim.

$$S = \int d^D x \sqrt{|g|} \left\{ R - \frac{1}{2} G_{ij}(\phi) \partial\phi^i \partial\phi^j \right\} .$$

# Branes as geodesics on moduli space

- ▶ E.o.m.'s for the scalars decouple from these for the metric. The e.o.m.'s for the scalars reduce to *geodesic equations* in the moduli space with metric  $G_{ij}(\phi)$ .
- ▶ Main difference between time-like and space-like branes:

time-like branes	space-like branes
reduction includes time	reduction does not include time
$ds_D^2 = f^2(r)dr^2 + g^2(r)g_{ab}dx^a dx^b$	$ds_D^2 = -f^2(t)dt^2 + g^2(t)g_{ab}dx^a dx^b$
pseudo-Riem. moduli space	Riem. moduli space
$\frac{G}{H^*}$ with $H^*$ non-compact	$\frac{G}{H}$ with $H$ compact
$\ v\ ^2 > 0, < 0, = 0$	$\ v\ ^2 > 0$
relevant for black holes	relevant for cosmologies

# Branes as geodesics on moduli space

- ▶ E.o.m.'s for the scalars decouple from these for the metric. The e.o.m.'s for the scalars reduce to *geodesic equations* in the moduli space with metric  $G_{ij}(\phi)$ .
- ▶ Main difference between time-like and space-like branes:

time-like branes	space-like branes
reduction includes time	reduction does not include time
$ds_D^2 = f^2(r)dr^2 + g^2(r)g_{ab}dx^a dx^b$	$ds_D^2 = -f^2(t)dt^2 + g^2(t)g_{ab}dx^a dx^b$
pseudo-Riem. moduli space	Riem. moduli space
$\frac{G}{H^*}$ with $H^*$ non-compact	$\frac{G}{H}$ with $H$ compact
$\ v\ ^2 > 0, < 0, = 0$	$\ v\ ^2 > 0$
relevant for black holes	relevant for cosmologies

# The geodesic equations in Lax pair form

- ▶ Consider a symmetric space  $G/H$  (Riem. or pseudo-Riem.). The Cartan decomposition reads

$$\begin{aligned}\mathbb{G} &= \mathbb{H} + \mathbb{K}, \\ [\mathbb{H}, \mathbb{H}] &\subset \mathbb{H}, \quad [\mathbb{H}, \mathbb{K}] \subset \mathbb{K}, \quad [\mathbb{K}, \mathbb{K}] \subset \mathbb{H}.\end{aligned}$$

- ▶ Upon choosing a coset representative  $\mathbb{L}(\phi^I(t))$ , one can build the Maurer-Cartan form

$$\Omega = \mathbb{L}^{-1} \frac{d}{dt} \mathbb{L} = \dot{\phi}^J \mathbb{L}^{-1} \frac{\partial}{\partial \phi^J} \mathbb{L} = W + V,$$

with  $W \in \mathbb{H}$ ,  $V \in \mathbb{K}$ .

- ▶ The scalar field action reads

$$S = \int dt \operatorname{Tr}(VV) \propto \int dt G_{IJ}(\phi) \dot{\phi}^I \dot{\phi}^J.$$

- ▶ Varying this action, one is led to the following equations of motion:

$$\frac{d}{dt} V = [V, W].$$

# The geodesic equations in Lax pair form

- ▶ Consider a symmetric space  $G/H$  (Riem. or pseudo-Riem.). The Cartan decomposition reads

$$\begin{aligned}\mathbb{G} &= \mathbb{H} + \mathbb{K}, \\ [\mathbb{H}, \mathbb{H}] &\subset \mathbb{H}, \quad [\mathbb{H}, \mathbb{K}] \subset \mathbb{K}, \quad [\mathbb{K}, \mathbb{K}] \subset \mathbb{H}.\end{aligned}$$

- ▶ Upon choosing a coset representative  $\mathbb{L}(\phi^I(t))$ , one can build the Maurer-Cartan form

$$\Omega = \mathbb{L}^{-1} \frac{d}{dt} \mathbb{L} = \dot{\phi}^I \mathbb{L}^{-1} \frac{\partial}{\partial \phi^I} \mathbb{L} = W + V,$$

with  $W \in \mathbb{H}$ ,  $V \in \mathbb{K}$ .

- ▶ The scalar field action reads

$$S = \int dt \operatorname{Tr}(VV) \propto \int dt G_{IJ}(\phi) \dot{\phi}^I \dot{\phi}^J.$$

- ▶ Varying this action, one is led to the following equations of motion:

$$\frac{d}{dt} V = [V, W].$$

# The geodesic equations in Lax pair form

- ▶ Consider a symmetric space  $G/H$  (Riem. or pseudo-Riem.). The Cartan decomposition reads

$$\begin{aligned}\mathbb{G} &= \mathbb{H} + \mathbb{K}, \\ [\mathbb{H}, \mathbb{H}] &\subset \mathbb{H}, \quad [\mathbb{H}, \mathbb{K}] \subset \mathbb{K}, \quad [\mathbb{K}, \mathbb{K}] \subset \mathbb{H}.\end{aligned}$$

- ▶ Upon choosing a coset representative  $\mathbb{L}(\phi^I(t))$ , one can build the Maurer-Cartan form

$$\Omega = \mathbb{L}^{-1} \frac{d}{dt} \mathbb{L} = \dot{\phi}^I \mathbb{L}^{-1} \frac{\partial}{\partial \phi^I} \mathbb{L} = W + V,$$

with  $W \in \mathbb{H}$ ,  $V \in \mathbb{K}$ .

- ▶ The scalar field action reads

$$S = \int dt \operatorname{Tr}(VV) \propto \int dt G_{IJ}(\phi) \dot{\phi}^I \dot{\phi}^J.$$

- ▶ Varying this action, one is led to the following equations of motion:

$$\frac{d}{dt} V = [V, W].$$



# The geodesic equations in Lax pair form

- ▶ Consider a symmetric space  $G/H$  (Riem. or pseudo-Riem.). The Cartan decomposition reads

$$\begin{aligned}\mathbb{G} &= \mathbb{H} + \mathbb{K}, \\ [\mathbb{H}, \mathbb{H}] &\subset \mathbb{H}, \quad [\mathbb{H}, \mathbb{K}] \subset \mathbb{K}, \quad [\mathbb{K}, \mathbb{K}] \subset \mathbb{H}.\end{aligned}$$

- ▶ Upon choosing a coset representative  $\mathbb{L}(\phi^I(t))$ , one can build the Maurer-Cartan form

$$\Omega = \mathbb{L}^{-1} \frac{d}{dt} \mathbb{L} = \dot{\phi}^I \mathbb{L}^{-1} \frac{\partial}{\partial \phi^I} \mathbb{L} = W + V,$$

with  $W \in \mathbb{H}$ ,  $V \in \mathbb{K}$ .

- ▶ The scalar field action reads

$$S = \int dt \operatorname{Tr}(VV) \propto \int dt G_{IJ}(\phi) \dot{\phi}^I \dot{\phi}^J.$$

- ▶ Varying this action, one is led to the following equations of motion:

$$\frac{d}{dt} V = [V, W].$$

# The geodesic equations in Lax pair form

- ▶ The equation

$$\frac{d}{dt}V = [V, W],$$

constitutes the so-called Lax equation. It reproduces the geodesic equations as a matrix differential equation.

- ▶ Note :  $V(t) = V(\phi(t), \dot{\phi}(t))$ ,  $W(t) = W(\phi(t), \dot{\phi}(t))$ .
- ▶ For symmetric spaces, one can work in *solvable gauge* :

$$\mathbb{L} = \exp b, \quad b \in \text{Borel algebra}.$$

” $\mathbb{L}$  = exponential of upper triangular matrix”.

- ▶ In solvable gauge

$$W = V_{>0} - V_{<0}.$$

- ▶ The Lax equation, with  $W$  obeying the latter equation, can be solved algorithmically, for generic initial condition  $V(t=0) = V_0$ .

# The geodesic equations in Lax pair form

- ▶ The equation

$$\frac{d}{dt}V = [V, W],$$

constitutes the so-called Lax equation. It reproduces the geodesic equations as a matrix differential equation.

- ▶ Note :  $V(t) = V(\phi(t), \dot{\phi}(t))$ ,  $W(t) = W(\phi(t), \dot{\phi}(t))$ .

- ▶ For symmetric spaces, one can work in *solvable gauge* :

$$\mathbb{L} = \exp b, \quad b \in \text{Borel algebra}.$$

" $\mathbb{L}$  = exponential of upper triangular matrix".

- ▶ In solvable gauge

$$W = V_{>0} - V_{<0}.$$

- ▶ The Lax equation, with  $W$  obeying the latter equation, can be solved algorithmically, for generic initial condition  $V(t=0) = V_0$ .

# The geodesic equations in Lax pair form

- ▶ The equation

$$\frac{d}{dt}V = [V, W],$$

constitutes the so-called Lax equation. It reproduces the geodesic equations as a matrix differential equation.

- ▶ Note :  $V(t) = V(\phi(t), \dot{\phi}(t))$ ,  $W(t) = W(\phi(t), \dot{\phi}(t))$ .
- ▶ For symmetric spaces, one can work in *solvable gauge* :

$$\mathbb{L} = \exp b, \quad b \in \text{Borel algebra}.$$

” $\mathbb{L}$  = exponential of upper triangular matrix”.

- ▶ In solvable gauge

$$W = V_{>0} - V_{<0}.$$

- ▶ The Lax equation, with  $W$  obeying the latter equation, can be solved algorithmically, for generic initial condition  $V(t=0) = V_0$ .

# The geodesic equations in Lax pair form

- ▶ The equation

$$\frac{d}{dt}V = [V, W],$$

constitutes the so-called Lax equation. It reproduces the geodesic equations as a matrix differential equation.

- ▶ Note :  $V(t) = V(\phi(t), \dot{\phi}(t))$ ,  $W(t) = W(\phi(t), \dot{\phi}(t))$ .
- ▶ For symmetric spaces, one can work in *solvable gauge* :

$$\mathbb{L} = \exp b, \quad b \in \text{Borel algebra}.$$

” $\mathbb{L}$  = exponential of upper triangular matrix”.

- ▶ In solvable gauge

$$W = V_{>0} - V_{<0}.$$

- ▶ The Lax equation, with  $W$  obeying the latter equation, can be solved algorithmically, for generic initial condition  $V(t=0) = V_0$ .

# The geodesic equations in Lax pair form

- ▶ The equation

$$\frac{d}{dt}V = [V, W],$$

constitutes the so-called Lax equation. It reproduces the geodesic equations as a matrix differential equation.

- ▶ Note :  $V(t) = V(\phi(t), \dot{\phi}(t))$ ,  $W(t) = W(\phi(t), \dot{\phi}(t))$ .
- ▶ For symmetric spaces, one can work in *solvable gauge* :

$$\mathbb{L} = \exp b, \quad b \in \text{Borel algebra}.$$

” $\mathbb{L}$  = exponential of upper triangular matrix”.

- ▶ In solvable gauge

$$W = V_{>0} - V_{<0}.$$

- ▶ The Lax equation, with  $W$  obeying the latter equation, can be solved algorithmically, for generic initial condition  $V(t=0) = V_0$ .

# Initial conditions

- ▶ In order to solve the Lax equation, one needs to specify an initial condition  $V_0$ . This is taken to be an arbitrary (constant) element of  $\mathbb{K}$ .
- ▶ In general :

$$\mathbb{H} = \text{Span} \{E^\alpha + \theta(E^\alpha)\} ,$$

$$\mathbb{K} = \text{Span} \{H_i, (E^\alpha - \theta(E^\alpha))\} .$$

with

$$\text{space - like branes : } \theta(E^\alpha) = -E^{-\alpha} = -(E^\alpha)^T ,$$

$$\text{time - like branes : } \theta(E^\alpha) = -(-1)^{\beta_0(\alpha)} E^{-\alpha} = -(-1)^{\beta_0(\alpha)} (E^\alpha)^T .$$

$\beta_0(\alpha)$  = grading of root  $\alpha$  with respect to a generator associated with the internal time direction. It takes on values 0, 1, 2 on positive values.

# Initial conditions

- ▶ In order to solve the Lax equation, one needs to specify an initial condition  $V_0$ . This is taken to be an arbitrary (constant) element of  $\mathbb{K}$ .
- ▶ In general :

$$\mathbb{H} = \text{Span} \{E^\alpha + \theta(E^\alpha)\} ,$$

$$\mathbb{K} = \text{Span} \{H_i, (E^\alpha - \theta(E^\alpha))\} .$$

with

$$\text{space-like branes : } \theta(E^\alpha) = -E^{-\alpha} = -(E^\alpha)^T ,$$

$$\text{time-like branes : } \theta(E^\alpha) = -(-1)^{\beta_0(\alpha)} E^{-\alpha} = -(-1)^{\beta_0(\alpha)} (E^\alpha)^T .$$

$\beta_0(\alpha)$  = grading of root  $\alpha$  with respect to a generator associated with the internal time direction. It takes on values 0, 1, 2 on positive values.



# Initial conditions

- ▶ Strategy for parametrizing initial values : parametrize  $V_0$  as

$$V_0 = h(\exp Q_N)h^{-1}, \quad h \in H,$$

with  $Q_N$  the so-called *normal form*.

- ▶ Space-like branes : elements of  $\mathbb{K}$  are either diagonal, or symmetric  $\Rightarrow$  they can be diagonalized using  $H$ -transformations. The eigenvalues are moreover real.
- ▶ Time-like branes : elements of  $\mathbb{K}$  are either diagonal, symmetric or anti-symmetric. The normal form is no longer diagonal. Generically ([Bergshoeff et al. : arXiv:0806.2310](#))

$$Q_N \in \left\{ \left( \begin{array}{c} \mathfrak{sl}(2, \mathbb{R}) \\ \mathfrak{so}(1, 1) \end{array} \right)^p \times \mathfrak{so}(1, 1)^q \right\} \oplus \text{Nil}$$

complex eigval.   real eigval.   nilpotent el.

# Initial conditions

- ▶ Strategy for parametrizing initial values : parametrize  $V_0$  as

$$V_0 = h(\exp Q_N)h^{-1}, \quad h \in H,$$

with  $Q_N$  the so-called *normal form*.

- ▶ Space-like branes : elements of  $\mathbb{K}$  are either diagonal, or symmetric  $\Rightarrow$  they can be diagonalized using  $H$ -transformations. The eigenvalues are moreover real.
- ▶ Time-like branes : elements of  $\mathbb{K}$  are either diagonal, symmetric or anti-symmetric. The normal form is no longer diagonal. Generically ([Bergshoeff et al. : arXiv:0806.2310](#))

$$Q_N \in \left\{ \left( \begin{array}{c} \mathfrak{sl}(2, \mathbb{R}) \\ \mathfrak{so}(1, 1) \end{array} \right)^p \times \mathfrak{so}(1, 1)^q \right\} \oplus \text{Nil}$$

complex eigval.   real eigval.   nilpotent el.

# Initial conditions

- ▶ Strategy for parametrizing initial values : parametrize  $V_0$  as

$$V_0 = h(\exp Q_N)h^{-1}, \quad h \in H,$$

with  $Q_N$  the so-called *normal form*.

- ▶ Space-like branes : elements of  $\mathbb{K}$  are either diagonal, or symmetric  $\Rightarrow$  they can be diagonalized using  $H$ -transformations. The eigenvalues are moreover real.
- ▶ Time-like branes : elements of  $\mathbb{K}$  are either diagonal, symmetric or anti-symmetric. The normal form is no longer diagonal. Generically ([Bergshoeff et al. : arXiv:0806.2310](#))

$$Q_N \in \left\{ \left( \frac{\mathfrak{sl}(2, \mathbb{R})}{\mathfrak{so}(1, 1)} \right)^p \times \mathfrak{so}(1, 1)^q \right\} \oplus \text{Nil}$$

complex eigval.   real eigval.   nilpotent el.

# The simplest example : $S\ell(2, \mathbb{R})$

- ▶ Generators, coset representative and Lax operator

$$H = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad E = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad \mathbb{L} = e^{\chi(t)E} e^{\frac{\phi(t)}{2}H}.$$
$$V = \begin{pmatrix} \frac{1}{2}\phi'[t] & \pm\frac{1}{2}e^{-\phi[t]}\chi'[t] \\ \frac{1}{2}e^{-\phi[t]}\chi'[t] & -\frac{1}{2}\phi'[t] \end{pmatrix}$$

- ▶ Space-like branes ( $S\ell(2, \mathbb{R})/SO(2)$ ):

$$\mathbb{H} = \text{Span} \{ (E - E^T) \}, \quad \mathbb{K} = \text{Span} \left\{ H, \frac{1}{\sqrt{2}}(E + E^T) \right\},$$
$$V_0 = \begin{pmatrix} a & b \\ b & -a \end{pmatrix}, \quad a, b \in \mathbb{R}$$

$V_0$  is always diagonalizable with real eigenvalues  $\pm\sqrt{a^2 + b^2}$ .

# The simplest example : $S\ell(2, \mathbb{R})$

- ▶ Generators, coset representative and Lax operator

$$H = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad E = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad \mathbb{L} = e^{\chi(t)E} e^{\frac{\phi(t)}{2}H}.$$
$$V = \begin{pmatrix} \frac{1}{2}\phi'[t] & \pm\frac{1}{2}e^{-\phi[t]}\chi'[t] \\ \frac{1}{2}e^{-\phi[t]}\chi'[t] & -\frac{1}{2}\phi'[t] \end{pmatrix}$$

- ▶ Space-like branes ( $S\ell(2, \mathbb{R})/SO(2)$ ):

$$\mathbb{H} = \text{Span} \{ (E - E^T) \}, \quad \mathbb{K} = \text{Span} \left\{ H, \frac{1}{\sqrt{2}}(E + E^T) \right\},$$
$$V_0 = \begin{pmatrix} a & b \\ b & -a \end{pmatrix}, \quad a, b \in \mathbb{R}$$

$V_0$  is always diagonalizable with real eigenvalues  $\pm\sqrt{a^2 + b^2}$ .

# The simplest example : $S \ell(2, \mathbb{R})$

- ▶ Time-like branes ( $S \ell(2, \mathbb{R}) / SO(1, 1)$ ):

$$\mathbb{H} = \text{Span} \{ (E + E^T) \} , \quad \mathbb{K} = \text{Span} \left\{ H, \frac{1}{\sqrt{2}}(E - E^T) \right\} ,$$
$$V_0 = \begin{pmatrix} a & b \\ -b & -a \end{pmatrix} , \quad a, b \in \mathbb{R}$$

We now have to distinguish three cases:

- $a^2 > b^2$  : normal form is diagonal with 2 real eigenvalues :  
 $\lambda_{\pm} = \pm \sqrt{a^2 - b^2}$ . Corresponds to geodesics with positive norm squared.
- $a^2 < b^2$  : 2 complex eigenvalues  $\lambda, \bar{\lambda} = \pm i \sqrt{a^2 - b^2}$ . Corresponds to geodesics with negative norm squared.
- $a^2 = b^2$  :

$$V_0 \propto \begin{pmatrix} 1 & 1 \\ -1 & -1 \end{pmatrix}$$

This case is nilpotent of degree 2 :  $V_0^2 = 0$ . Corresponds to null geodesics.

# The simplest example : $S \ell(2, \mathbb{R})$

- ▶ Time-like branes ( $S \ell(2, \mathbb{R}) / SO(1, 1)$ ):

$$\mathbb{H} = \text{Span} \{ (E + E^T) \}, \quad \mathbb{K} = \text{Span} \left\{ H, \frac{1}{\sqrt{2}}(E - E^T) \right\},$$
$$V_0 = \begin{pmatrix} a & b \\ -b & -a \end{pmatrix}, \quad a, b \in \mathbb{R}$$

We now have to distinguish three cases:

- $a^2 > b^2$  : normal form is diagonal with 2 real eigenvalues :  
 $\lambda_{\pm} = \pm \sqrt{a^2 - b^2}$ . Corresponds to geodesics with positive norm squared.
- $a^2 < b^2$  : 2 complex eigenvalues  $\lambda, \bar{\lambda} = \pm i \sqrt{a^2 - b^2}$ . Corresponds to geodesics with negative norm squared.
- $a^2 = b^2$  :

$$V_0 \propto \begin{pmatrix} 1 & 1 \\ -1 & -1 \end{pmatrix}$$

This case is nilpotent of degree 2 :  $V_0^2 = 0$ . Corresponds to null geodesics.

# The simplest example : $S\ell(2, \mathbb{R})$

- ▶ Time-like branes ( $S\ell(2, \mathbb{R})/SO(1, 1)$ ):

$$\mathbb{H} = \text{Span} \{ (E + E^T) \}, \quad \mathbb{K} = \text{Span} \left\{ H, \frac{1}{\sqrt{2}}(E - E^T) \right\},$$

$$V_0 = \begin{pmatrix} a & b \\ -b & -a \end{pmatrix}, \quad a, b \in \mathbb{R}$$

We now have to distinguish three cases:

- $a^2 > b^2$  : normal form is diagonal with 2 real eigenvalues :  
 $\lambda_{\pm} = \pm\sqrt{a^2 - b^2}$ . Corresponds to geodesics with positive norm squared.
- $a^2 < b^2$  : 2 complex eigenvalues  $\lambda, \bar{\lambda} = \pm i\sqrt{a^2 - b^2}$ . Corresponds to geodesics with negative norm squared.
- $a^2 = b^2$  :

$$V_0 \propto \begin{pmatrix} 1 & 1 \\ -1 & -1 \end{pmatrix}$$

This case is nilpotent of degree 2 :  $V_0^2 = 0$ . Corresponds to null geodesics.



# A universal integration algorithm

- ▶ Mathematicians have developed an integration algorithm that solves the Lax equation (Kodama et al. : [solv-int/9505004](#), [solv-int/9506005](#)).
- ▶ This algorithm is **universal** : works both for Riemannian and pseudo-Riemannian cosets. The result is a solution  $V_{\text{sol}}(t)$  such that

$$\frac{d}{dt} V_{\text{sol}}(t) = [V_{\text{sol}}(t), V_{\text{sol} > 0}(t) - V_{\text{sol} < 0}(t)] .$$

- ▶ The version of Kodama et al. only incorporates diagonalizable initial conditions (real/complex eigenvalues).
- ▶ We gave however an integration formula that works for generic initial conditions, so including the nilpotent cases (Chemissany et al. 2009). Result:

$$V_{pq} = V_{pq}(t, V_0) .$$

- ▶ Comparing  $V_{\text{sol}}(t)$  with the expression of  $V(\phi, \dot{\phi}) \Rightarrow$  iterative system of first order equations (solvable gauge!). Can be solved easily, leading to solutions for the scalar fields.

# A universal integration algorithm

- ▶ Mathematicians have developed an integration algorithm that solves the Lax equation (Kodama et al. : [solv-int/9505004](#), [solv-int/9506005](#)).
- ▶ This algorithm is **universal** : works both for Riemannian and pseudo-Riemannian cosets. The result is a solution  $V_{\text{sol}}(t)$  such that

$$\frac{d}{dt}V_{\text{sol}}(t) = [V_{\text{sol}}(t), V_{\text{sol} > 0}(t) - V_{\text{sol} < 0}(t)] .$$

- ▶ The version of Kodama et al. only incorporates diagonalizable initial conditions (real/complex eigenvalues).
- ▶ We gave however an integration formula that works for generic initial conditions, so including the nilpotent cases (Chemissany et al. 2009). Result:

$$V_{pq} = V_{pq}(t, V_0) .$$

- ▶ Comparing  $V_{\text{sol}}(t)$  with the expression of  $V(\phi, \dot{\phi}) \Rightarrow$  iterative system of first order equations (solvable gauge!). Can be solved easily, leading to solutions for the scalar fields.

# A universal integration algorithm

- ▶ Mathematicians have developed an integration algorithm that solves the Lax equation (Kodama et al. : [solv-int/9505004](#), [solv-int/9506005](#)).
- ▶ This algorithm is **universal** : works both for Riemannian and pseudo-Riemannian cosets. The result is a solution  $V_{\text{sol}}(t)$  such that

$$\frac{d}{dt} V_{\text{sol}}(t) = [V_{\text{sol}}(t), V_{\text{sol} > 0}(t) - V_{\text{sol} < 0}(t)] .$$

- ▶ The version of Kodama et al. only incorporates diagonalizable initial conditions (real/complex eigenvalues).
- ▶ We gave however an integration formula that works for generic initial conditions, so including the nilpotent cases (Chemissany et al. 2009).  
Result:

$$V_{pq} = V_{pq}(t, V_0) .$$

- ▶ Comparing  $V_{\text{sol}}(t)$  with the expression of  $V(\phi, \dot{\phi}) \Rightarrow$  iterative system of first order equations (solvable gauge!). Can be solved easily, leading to solutions for the scalar fields.

# A universal integration algorithm

- ▶ Mathematicians have developed an integration algorithm that solves the Lax equation ([Kodama et al. : solv-int/9505004, solv-int/9506005](#)).
- ▶ This algorithm is **universal** : works both for Riemannian and pseudo-Riemannian cosets. The result is a solution  $V_{\text{sol}}(t)$  such that

$$\frac{d}{dt} V_{\text{sol}}(t) = [V_{\text{sol}}(t), V_{\text{sol} > 0}(t) - V_{\text{sol} < 0}(t)] .$$

- ▶ The version of Kodama et al. only incorporates diagonalizable initial conditions (real/complex eigenvalues).
- ▶ We gave however an integration formula that works for generic initial conditions, so including the nilpotent cases ([Chemissany et al. 2009](#)).  
Result:

$$V_{pq} = V_{pq}(t, V_0) .$$

- ▶ Comparing  $V_{\text{sol}}(t)$  with the expression of  $V(\phi, \dot{\phi}) \Rightarrow$  iterative system of first order equations (solvable gauge!). Can be solved easily, leading to solutions for the scalar fields.

# A universal integration algorithm

- ▶ Mathematicians have developed an integration algorithm that solves the Lax equation ([Kodama et al. : solv-int/9505004, solv-int/9506005](#)).
- ▶ This algorithm is **universal** : works both for Riemannian and pseudo-Riemannian cosets. The result is a solution  $V_{\text{sol}}(t)$  such that

$$\frac{d}{dt}V_{\text{sol}}(t) = [V_{\text{sol}}(t), V_{\text{sol} > 0}(t) - V_{\text{sol} < 0}(t)] .$$

- ▶ The version of Kodama et al. only incorporates diagonalizable initial conditions (real/complex eigenvalues).
- ▶ We gave however an integration formula that works for generic initial conditions, so including the nilpotent cases ([Chemissany et al. 2009](#)).  
Result:

$$V_{pq} = V_{pq}(t, V_0) .$$

- ▶ Comparing  $V_{\text{sol}}(t)$  with the expression of  $V(\phi, \dot{\phi}) \Rightarrow$  iterative system of first order equations (solvable gauge!). Can be solved easily, leading to solutions for the scalar fields.

# Lax Integration algorithms

- ▶ All integration algorithms developed so far focus on giving solution for the Lax operator  $V$ , which is somewhat **sufficient** to obtain the solutions for the scalar fields.
- ▶ However, this requires solving a second order differential equations which can be solved explicitly.
- ▶ For practical reasons, we found it desirable to circumvent this second integration step by proposing and proving an integration formula ([Chemissany et al. 2010](#)).

# Lax Integration algorithms

- ▶ All integration algorithms developed so far focus on giving solution for the Lax operator  $V$ , which is somewhat **sufficient** to obtain the solutions for the scalar fields.
- ▶ However, this requires solving a second order differential equations which can be solved explicitly.
- ▶ For practical reasons, we found it desirable to circumvent this second integration step by proposing and proving an integration formula ([Chemissany et al. 2010](#)).

# Lax Integration algorithms

- ▶ All integration algorithms developed so far focus on giving solution for the Lax operator  $V$ , which is somewhat **sufficient** to obtain the solutions for the scalar fields.
- ▶ However, this requires solving a second order differential equations which can be solved explicitly.
- ▶ For practical reasons, we found it desirable to circumvent this second integration step by proposing and proving an integration formula ([Chemissany et al. 2010](#)).



# Lax Integration algorithms

- ▶ All integration algorithms developed so far focus on giving solution for the Lax operator  $V$ , which is somewhat **sufficient** to obtain the solutions for the scalar fields.
- ▶ However, this requires solving a second order differential equations which can be solved explicitly.
- ▶ For practical reasons, we found it desirable to circumvent this second integration step by proposing and proving an integration formula ([Chemissany et al. 2010](#)).

# Liouville Integrability

- ▶ Proving an integration formula is one thing: establishing the complete integrability of the geodesic equations is a separate issue.
- ▶ **Liouville Integrability**: is the statement that there exist  $n$  functionally independent constant of motion  $\mathcal{H}_i(Z)$  (hamiltonians):

$$\{\mathcal{H}_i, \mathcal{H}_j\} = 0$$

- ▶ The geodesic Lagrangian reads

$$\mathcal{L} = \frac{1}{2}g_{AB}Y^AY^B = \frac{1}{2}g_{ij}\dot{\phi}^i\dot{\phi}^j, \quad V = Y^AK_A$$

- ▶ Phase space variables are denoted by  $\{\phi^i, P_j\}$ , thereby the geodesic Eqs take the form

$$\dot{Z} + \{\mathcal{H}, Z\} = 0.$$

- ▶ Using the poisson bracket on the phase space and  $Y^A = g^{AB}V_B^iP_i$  together with MC Eqs, we obtain

$$\{Y_A, Y_B\} = -f_{AB}{}^CY_C$$

This is the natural Poisson brackets on  $sol^v^*$  induced by the Lie algebra.

# Liouville Integrability

- ▶ Proving an integration formula is one thing: establishing the complete integrability of the geodesic equations is a separate issue.
- ▶ **Liouville Integrability**: is the statement that there exist  $n$  functionally independent constant of motion  $\mathcal{H}_i(Z)$  (hamiltonians):

$$\{\mathcal{H}_i, \mathcal{H}_j\} = 0$$

- ▶ The geodesic Lagrangian reads

$$\mathcal{L} = \frac{1}{2}g_{AB}Y^AY^B = \frac{1}{2}g_{ij}\dot{\phi}^i\dot{\phi}^j, \quad V = Y^AK_A$$

- ▶ Phase space variables are denoted by  $\{\phi^i, P_j\}$ , thereby the geodesic Eqs take the form

$$\dot{Z} + \{\mathcal{H}, Z\} = 0.$$

- ▶ Using the poisson bracket on the phase space and  $Y^A = g^{AB}V_B^iP_i$  together with MC Eqs, we obtain

$$\{Y_A, Y_B\} = -f_{AB}^C Y_C$$

This is the natural Poisson brackets on  $sol^v^*$  induced by the Lie algebra.

# Liouville Integrability

- ▶ Proving an integration formula is one thing: establishing the complete integrability of the geodesic equations is a separate issue.
- ▶ **Liouville Integrability**: is the statement that there exist  $n$  functionally independent constant of motion  $\mathcal{H}_i(Z)$  (hamiltonians):

$$\{\mathcal{H}_i, \mathcal{H}_j\} = 0$$

- ▶ The geodesic Lagrangian reads

$$\mathcal{L} = \frac{1}{2}g_{AB}Y^AY^B = \frac{1}{2}g_{ij}\dot{\phi}^i\dot{\phi}^j, \quad V = Y^AK_A$$

- ▶ Phase space variables are denoted by  $\{\phi^i, P_j\}$ , thereby the geodesic Eqs take the form

$$\dot{Z} + \{\mathcal{H}, Z\} = 0.$$

- ▶ Using the poisson bracket on the phase space and  $Y^A = g^{AB}V_B^iP_i$  together with MC Eqs, we obtain

$$\{Y_A, Y_B\} = -f_{AB}^CY_C$$

This is the natural Poisson brackets on  $sol^v^*$  induced by the Lie algebra.

# Liouville Integrability

- ▶ Proving an integration formula is one thing: establishing the complete integrability of the geodesic equations is a separate issue.
- ▶ **Liouville Integrability**: is the statement that there exist  $n$  functionally independent constant of motion  $\mathcal{H}_i(Z)$  (hamiltonians):

$$\{\mathcal{H}_i, \mathcal{H}_j\} = 0$$

- ▶ The geodesic Lagrangian reads

$$\mathcal{L} = \frac{1}{2}g_{AB}Y^AY^B = \frac{1}{2}g_{ij}\dot{\phi}^i\dot{\phi}^j, \quad V = Y^AK_A$$

- ▶ Phase space variables are denoted by  $\{\phi^i, P_j\}$ , thereby the geodesic Eqs take the form

$$\dot{Z} + \{\mathcal{H}, Z\} = 0.$$

- ▶ Using the poisson bracket on the phase space and  $Y^A = g^{AB}V_B^iP_i$  together with MC Eqs, we obtain

$$\{Y_A, Y_B\} = -f_{AB}{}^CY_C$$

This is the natural Poisson brackets on  $solv^*$  induced by the Lie algebra.

# Liouville Integrability

- ▶ Proving an integration formula is one thing: establishing the complete integrability of the geodesic equations is a separate issue.
- ▶ **Liouville Integrability**: is the statement that there exist  $n$  functionally independent constant of motion  $\mathcal{H}_i(Z)$  (hamiltonians):

$$\{\mathcal{H}_i, \mathcal{H}_j\} = 0$$

- ▶ The geodesic Lagrangian reads

$$\mathcal{L} = \frac{1}{2}g_{AB}Y^AY^B = \frac{1}{2}g_{ij}\dot{\phi}^i\dot{\phi}^j, \quad V = Y^AK_A$$

- ▶ Phase space variables are denoted by  $\{\phi^i, P_j\}$ , thereby the geodesic Eqs take the form

$$\dot{Z} + \{\mathcal{H}, Z\} = 0.$$

- ▶ Using the poisson bracket on the phase space and  $Y^A = g^{AB}V_B^iP_i$  together with MC Eqs, we obtain

$$\{Y_A, Y_B\} = -f_{AB}{}^CY_C$$

This is the natural Poisson brackets on  $solv^*$  induced by the Lie algebra.

# Liouville Integrability

- ▶ Proving an integration formula is one thing: establishing the complete integrability of the geodesic equations is a separate issue.
- ▶ **Liouville Integrability**: is the statement that there exist  $n$  functionally independent constant of motion  $\mathcal{H}_i(Z)$  (hamiltonians):

$$\{\mathcal{H}_i, \mathcal{H}_j\} = 0$$

- ▶ The geodesic Lagrangian reads

$$\mathcal{L} = \frac{1}{2}g_{AB}Y^AY^B = \frac{1}{2}g_{ij}\dot{\phi}^i\dot{\phi}^j, \quad V = Y^AK_A$$

- ▶ Phase space variables are denoted by  $\{\phi^i, P_j\}$ , thereby the geodesic Eqs take the form

$$\dot{Z} + \{\mathcal{H}, Z\} = 0.$$

- ▶ Using the poisson bracket on the phase space and  $Y^A = g^{AB}V_B^iP_i$  together with MC Eqs, we obtain

$$\{Y_A, Y_B\} = -f_{AB}^C Y_C$$

This is the natural Poisson brackets on  $solv^*$  induced by the Lie algebra.

# Liouville Integrability

- ▶ **Noether Charge:** Consider the following matrix

$$Q = \mathbb{L}(\tau)V(\tau)\mathbb{L}(\tau)^{-1}, \quad \frac{dQ}{d\tau} = 0$$

The  $n$  components of Noether charge matrix defined by

$$Q_A \sim \text{Tr}(QT_A)$$

- ▶ One can derive the following relations between  $Q_A$  and  $Y_A$

$$Q_A = \mathbb{L}_A^B Y_B$$

- ▶ This implies

$$\{Q_A, Y_B\} = 0, \quad \{Q_A, Q_B\} = f_{AB}^C Q_C$$



# Liouville Integrability

- ▶ **Noether Charge:** Consider the following matrix

$$Q = \mathbb{L}(\tau)V(\tau)\mathbb{L}(\tau)^{-1}, \quad \frac{dQ}{d\tau} = 0$$

The  $n$  components of Noether charge matrix defined by

$$Q_A \sim \text{Tr}(QT_A)$$

- ▶ One can derive the following relations between  $Q_A$  and  $Y_A$

$$Q_A = \mathbb{L}_A{}^B Y_B$$

- ▶ This implies

$$\{Q_A, Y_B\} = 0, \quad \{Q_A, Q_B\} = f_{AB}{}^C Q_C$$

# Liouville Integrability

- ▶ **Noether Charge:** Consider the following matrix

$$Q = \mathbb{L}(\tau)V(\tau)\mathbb{L}(\tau)^{-1}, \quad \frac{dQ}{d\tau} = 0$$

The  $n$  components of Noether charge matrix defined by

$$Q_A \sim \text{Tr}(QT_A)$$

- ▶ One can derive the following relations between  $Q_A$  and  $Y_A$

$$Q_A = \mathbb{L}_A{}^B Y_B$$

- ▶ This implies

$$\{Q_A, Y_B\} = 0, \quad \{Q_A, Q_B\} = f_{AB}{}^C Q_C$$

# Liouville Integrability

- ▶ **Noether Charge:** Consider the following matrix

$$Q = \mathbb{L}(\tau)V(\tau)\mathbb{L}(\tau)^{-1}, \quad \frac{dQ}{d\tau} = 0$$

The  $n$  components of Noether charge matrix defined by

$$Q_A \sim \text{Tr}(QT_A)$$

- ▶ One can derive the following relations between  $Q_A$  and  $Y_A$

$$Q_A = \mathbb{L}_A^B Y_B$$

- ▶ This implies

$$\{Q_A, Y_B\} = 0, \quad \{Q_A, Q_B\} = f_{AB}^C Q_C$$

# Liouville Integrability

- ▶ **Proof:** Establishing Liouville integrability of the *first order problem*

$$\dot{Y}_A + \{\mathcal{H}, Y_A\} = 0$$

- ▶ Poisson bracket on the dual Lie algebra  $Solv^*$  is **degenerate**, integrability implies the existence of symplectic foliation for which the hamiltonian flows are integrable on the symplectic leaves.
- ▶ Each leaf is nothing but the co-adjoint orbit of an element ( $Y^A$ ) of  $Solv^*$ .
- ▶ Denote

$$\dim(coset) = n, \quad \dim(leaf) = 2h_O, \quad 2h_O = \text{rank}(f_{AB}{}^C Y_C)$$

- ▶ We proved the existence of  $(n - h_O)$  constants of motion in involution where:  
 $h_O \rightarrow$  corresponds to Hamilt. in involution on symplectic leaf.  
 $n - 2h_O \rightarrow$  are referred to as **Casimirs** defined as

$$\{\mathcal{H}(Y), Y_A\} = 0.$$

# Liouville Integrability

- ▶ **Proof:** Establishing Liouville integrability of the *first order problem*

$$\dot{Y}_A + \{\mathcal{H}, Y_A\} = 0$$

- ▶ Poisson bracket on the dual Lie algebra  $Solv^*$  is **degenerate**, integrability implies the existence of symplectic foliation for which the hamiltonian flows are integrable on the symplectic leaves.
- ▶ Each leaf is nothing but the co-adjoint orbit of an element ( $Y^A$ ) of  $Solv^*$ .
- ▶ Denote

$$\dim(\text{coset}) = n, \quad \dim(\text{leaf}) = 2h_O, \quad 2h_O = \text{rank}(f_{AB}{}^C Y_C)$$

- ▶ We proved the existence of  $(n - h_O)$  constants of motion in involution where:  
 $h_O \rightarrow$  corresponds to Hamilt. in involution on symplectic leaf.  
 $n - 2h_O \rightarrow$  are referred to as **Casimirs** defined as

$$\{\mathcal{H}(Y), Y_A\} = 0.$$

# Liouville Integrability

- ▶ **Proof:** Establishing Liouville integrability of the *first order problem*

$$\dot{Y}_A + \{\mathcal{H}, Y_A\} = 0$$

- ▶ Poisson bracket on the dual Lie algebra  $Solv^*$  is **degenerate**, integrability implies the existence of symplectic foliation for which the hamiltonian flows are integrable on the symplectic leaves.
- ▶ Each leaf is nothing but the co-adjoint orbit of an element ( $Y^A$ ) of  $Solv^*$ .
- ▶ Denote

$$\dim(coset) = n, \quad \dim(leaf) = 2h_O, \quad 2h_O = \text{rank}(f_{AB}{}^C Y_C)$$

- ▶ We proved the existence of  $(n - h_O)$  constants of motion in involution where:  
 $h_O \rightarrow$  corresponds to Hamilt. in involution on symplectic leaf.  
 $n - 2h_O \rightarrow$  are referred to as *Casimirs* defined as

$$\{\mathcal{H}(Y), Y_A\} = 0.$$

# Liouville Integrability

- ▶ **Proof:** Establishing Liouville integrability of the *first order problem*

$$\dot{Y}_A + \{\mathcal{H}, Y_A\} = 0$$

- ▶ Poisson bracket on the dual Lie algebra  $Solv^*$  is **degenerate**, integrability implies the existence of symplectic foliation for which the hamiltonian flows are integrable on the symplectic leaves.
- ▶ Each leaf is nothing but the co-adjoint orbit of an element ( $Y^A$ ) of  $Solv^*$ .
- ▶ Denote

$$\dim(\text{coset}) = n, \quad \dim(\text{leaf}) = 2h_O, \quad 2h_O = \text{rank}(f_{AB}{}^C Y_C)$$

- ▶ We proved the existence of  $(n - h_O)$  constants of motion in involution where:  
 $h_O \rightarrow$  corresponds to Hamilt. in involution on symplectic leaf.  
 $n - 2h_O \rightarrow$  are referred to as *Casimirs* defined as

$$\{\mathcal{H}(Y), Y_A\} = 0.$$

# Liouville Integrability

- ▶ **Proof:** Establishing Liouville integrability of the *first order problem*

$$\dot{Y}_A + \{\mathcal{H}, Y_A\} = 0$$

- ▶ Poisson bracket on the dual Lie algebra  $Solv^*$  is **degenerate**, integrability implies the existence of symplectic foliation for which the hamiltonian flows are integrable on the symplectic leaves.
- ▶ Each leaf is nothing but the co-adjoint orbit of an element ( $Y^A$ ) of  $Solv^*$ .
- ▶ Denote

$$\dim(coset) = n, \quad \dim(leaf) = 2h_O, \quad 2h_O = \text{rank}(f_{AB}{}^C Y_C)$$

- ▶ We proved the existence of  $(n - h_O)$  constants of motion in involution where:  
 $h_O \rightarrow$  corresponds to Hamilt. in involution on symplectic leaf.  
 $n - 2h_O \rightarrow$  are referred to as *Casimirs* defined as

$$\{\mathcal{H}(Y), Y_A\} = 0.$$



# Liouville Integrability

- ▶ **Proof:** Establishing Liouville integrability of the *first order problem*

$$\dot{Y}_A + \{\mathcal{H}, Y_A\} = 0$$

- ▶ Poisson bracket on the dual Lie algebra  $Solv^*$  is **degenerate**, integrability implies the existence of symplectic foliation for which the hamiltonian flows are integrable on the symplectic leaves.
- ▶ Each leaf is nothing but the co-adjoint orbit of an element ( $Y^A$ ) of  $Solv^*$ .
- ▶ Denote

$$\dim(coset) = n, \quad \dim(leaf) = 2h_O, \quad 2h_O = \text{rank}(f_{AB}{}^C Y_C)$$

- ▶ We proved the existence of  $(n - h_O)$  constants of motion in involution where:

$h_O \rightarrow$  corresponds to Hamilt. in involution on symplectic leaf.

$n - 2h_O \rightarrow$  are referred to as **Casimirs** defined as

$$\{\mathcal{H}(Y), Y_A\} = 0.$$

# Liouville Integrability

- ▶ Let's denote the Hamilt. and the Casimirs on the leaves by

$$\mathcal{H}_a(Y), \quad a = 1, \dots, h_O; \quad \mathcal{H}_\ell(Y), \quad \ell = 1, \dots, n - 2h_O.$$

- ▶ We find  $2(n - h_O)$  constants of motion which **Poisson commute**

$$\mathcal{H}_a(Y_A), \quad \mathcal{H}_\ell(Y_A), \quad \mathcal{H}_a(Q_A), \quad \mathcal{H}_\ell(Q_A),$$

where

- ▶ The  $\mathcal{H}_a(Q_A)$ , resp.  $\mathcal{H}_\ell(Q_A)$  are obtained by **replacing**  $Y_A$  by  $Q_A$  in  $\mathcal{H}_a(Y_A)$ ,  $\mathcal{H}_\ell(Y_A)$ .
- ▶ The only independent quantities are  $\mathcal{H}_a(Y)$ ,  $\mathcal{H}_\ell(Y)$  and  $\mathcal{H}_a(Q)$ . This therefore gives a total of

$$(n - h_O) + h_O = n$$

- ▶ Thereby proving Liouville integrability of the *second order problem*.

# Liouville Integrability

- ▶ Let's denote the Hamilt. and the Casimirs on the leaves by

$$\mathcal{H}_a(Y), \quad a = 1, \dots, h_O; \quad \mathcal{H}_\ell(Y), \quad \ell = 1, \dots, n - 2h_O.$$

- ▶ We find  $2(n - h_O)$  constants of motion which **Poisson commute**

$$\mathcal{H}_a(Y_A), \quad \mathcal{H}_\ell(Y_A), \quad \mathcal{H}_a(Q_A), \quad \mathcal{H}_\ell(Q_A),$$

where

- ▶ The  $\mathcal{H}_a(Q_A)$ , resp.  $\mathcal{H}_\ell(Q_A)$  are obtained by *replacing*  $Y_A$  by  $Q_A$  in  $\mathcal{H}_a(Y_A)$ ,  $\mathcal{H}_\ell(Y_A)$ .
- ▶ The only independent quantities are  $\mathcal{H}_a(Y)$ ,  $\mathcal{H}_\ell(Y)$  and  $\mathcal{H}_a(Q)$ . This therefore gives a total of

$$(n - h_O) + h_O = n$$

- ▶ Thereby proving Liouville integrability of the *second order problem*.

# Liouville Integrability

- ▶ Let's denote the Hamilt. and the Casimirs on the leaves by

$$\mathcal{H}_a(Y), \quad a = 1, \dots, h_O; \quad \mathcal{H}_\ell(Y), \quad \ell = 1, \dots, n - 2h_O.$$

- ▶ We find  $2(n - h_O)$  constants of motion which **Poisson commute**

$$\mathcal{H}_a(Y_A), \quad \mathcal{H}_\ell(Y_A), \quad \mathcal{H}_a(Q_A), \quad \mathcal{H}_\ell(Q_A),$$

where

- ▶ The  $\mathcal{H}_a(Q_A)$ , resp.  $\mathcal{H}_\ell(Q_A)$  are obtained by *replacing*  $Y_A$  by  $Q_A$  in  $\mathcal{H}_a(Y_A)$ ,  $\mathcal{H}_\ell(Y_A)$ .
- ▶ The only independent quantities are  $\mathcal{H}_a(Y)$ ,  $\mathcal{H}_\ell(Y)$  and  $\mathcal{H}_a(Q)$ . This therefore gives a total of

$$(n - h_O) + h_O = n$$

- ▶ Thereby proving Liouville integrability of the *second order problem*.

# Liouville Integrability

- ▶ Let's denote the Hamilt. and the Casimirs on the leaves by

$$\mathcal{H}_a(Y), \quad a = 1, \dots, h_O; \quad \mathcal{H}_\ell(Y), \quad \ell = 1, \dots, n - 2h_O.$$

- ▶ We find  $2(n - h_O)$  constants of motion which **Poisson commute**

$$\mathcal{H}_a(Y_A), \quad \mathcal{H}_\ell(Y_A), \quad \mathcal{H}_a(Q_A), \quad \mathcal{H}_\ell(Q_A),$$

where

- ▶ The  $\mathcal{H}_a(Q_A)$ , resp.  $\mathcal{H}_\ell(Q_A)$  are obtained by **replacing**  $Y_A$  by  $Q_A$  in  $\mathcal{H}_a(Y_A)$ ,  $\mathcal{H}_\ell(Y_A)$ .
- ▶ The only independent quantities are  $\mathcal{H}_a(Y)$ ,  $\mathcal{H}_\ell(Y)$  and  $\mathcal{H}_a(Q)$ . This therefore gives a total of

$$(n - h_O) + h_O = n$$

- ▶ Thereby proving Liouville integrability of the *second order problem*.

# Liouville Integrability

- ▶ Let's denote the Hamilt. and the Casimirs on the leaves by

$$\mathcal{H}_a(Y), \quad a = 1, \dots, h_O; \quad \mathcal{H}_\ell(Y), \quad \ell = 1, \dots, n - 2h_O.$$

- ▶ We find  $2(n - h_O)$  constants of motion which **Poisson commute**

$$\mathcal{H}_a(Y_A), \quad \mathcal{H}_\ell(Y_A), \quad \mathcal{H}_a(Q_A), \quad \mathcal{H}_\ell(Q_A),$$

where

- ▶ The  $\mathcal{H}_a(Q_A)$ , resp.  $\mathcal{H}_\ell(Q_A)$  are obtained by **replacing**  $Y_A$  by  $Q_A$  in  $\mathcal{H}_a(Y_A)$ ,  $\mathcal{H}_\ell(Y_A)$ .
- ▶ The only independent quantities are  $\mathcal{H}_a(Y)$ ,  $\mathcal{H}_\ell(Y)$  and  $\mathcal{H}_a(Q)$ . This therefore gives a total of

$$(n - h_O) + h_O = n$$

- ▶ Thereby proving Liouville integrability of the *second order problem*.

# Liouville Integrability

- ▶ Let's denote the Hamilt. and the Casimirs on the leaves by

$$\mathcal{H}_a(Y), \quad a = 1, \dots, h_O; \quad \mathcal{H}_\ell(Y), \quad \ell = 1, \dots, n - 2h_O.$$

- ▶ We find  $2(n - h_O)$  constants of motion which **Poisson commute**

$$\mathcal{H}_a(Y_A), \quad \mathcal{H}_\ell(Y_A), \quad \mathcal{H}_a(Q_A), \quad \mathcal{H}_\ell(Q_A),$$

where

- ▶ The  $\mathcal{H}_a(Q_A)$ , resp.  $\mathcal{H}_\ell(Q_A)$  are obtained by *replacing*  $Y_A$  by  $Q_A$  in  $\mathcal{H}_a(Y_A)$ ,  $\mathcal{H}_\ell(Y_A)$ .
- ▶ The only independent quantities are  $\mathcal{H}_a(Y)$ ,  $\mathcal{H}_\ell(Y)$  and  $\mathcal{H}_a(Q)$ . This therefore gives a total of

$$(n - h_O) + h_O = n$$

- ▶ Thereby proving Liouville integrability of the *second order problem*.

# Conclusion and Outlook

- ▶ We have established new insights into the solvability and integrability of the geodesic eqs following from reducing symmetric supergravities over the timelike direction.
- ▶ We have presented a recursive but closed formula for the coset representative describing a generic geodesic solution.
- ▶ Our results solve an open-standing question about the existence of a fake superpotential (Hamilton-Jacobi) for black hole solutions.
- ▶ Since Liouville Integrability implies HJ integrability we have proven the (local) **existence** of a fake superpotential for all stationary and spherically symmetric BH's.
- ▶ We have given the physical interpretation for most of the Hamiltonians, e.g. the polynomial constants keep track of the regularity and extremality of the solutions etc..
- ▶ We anticipate to investigate the Hamilt. in more involved models, such as the STU model.
- ▶ We believe that the  $n$  Hamilt. will provide a complete set of commuting observables for the quantum description of BH.



# Conclusion and Outlook

- ▶ We have established new insights into the solvability and integrability of the geodesic eqs following from reducing symmetric supergravities over the timelike direction.
- ▶ We have presented a recursive but closed formula for the coset representative describing a generic geodesic solution.
- ▶ Our results solve an open-standing question about the existence of a fake superpotential (Hamilton-Jacobi) for black hole solutions.
- ▶ Since Liouville Integrability implies HJ integrability we have proven the (local) **existence** of a fake superpotential for all stationary and spherically symmetric BH's.
- ▶ We have given the physical interpretation for most of the Hamiltonians, e.g. the polynomial constants keep track of the regularity and extremality of the solutions etc..
- ▶ We anticipate to investigate the Hamilt. in more involved models, such as the STU model.
- ▶ We believe that the  $n$  Hamilt. will provide a complete set of commuting observables for the quantum description of BH.

# Conclusion and Outlook

- ▶ We have established new insights into the solvability and integrability of the geodesic eqs following from reducing symmetric supergravities over the timelike direction.
- ▶ We have presented a recursive but closed formula for the coset representative describing a generic geodesic solution.
- ▶ Our results solve an open-standing question about the existence of a fake superpotential (Hamilton-Jacobi) for black hole solutions.
- ▶ Since Liouville Integrability implies HJ integrability we have proven the (local) **existence** of a fake superpotential for all stationary and spherically symmetric BH's.
- ▶ We have given the physical interpretation for most of the Hamiltonians, e.g. the polynomial constants keep track of the regularity and extremality of the solutions etc..
- ▶ We anticipate to investigate the Hamilt. in more involved models, such as the STU model.
- ▶ We believe that the  $n$  Hamilt. will provide a complete set of commuting observables for the quantum description of BH.

# Conclusion and Outlook

- ▶ We have established new insights into the solvability and integrability of the geodesic eqs following from reducing symmetric supergravities over the timelike direction.
- ▶ We have presented a recursive but closed formula for the coset representative describing a generic geodesic solution.
- ▶ Our results solve an open-standing question about the existence of a fake superpotential (Hamilton-Jacobi) for black hole solutions.
- ▶ Since Liouville Integrability implies HJ integrability we have proven the (local) **existence** of a fake superpotential for all stationary and spherically symmetric BH's.
- ▶ We have given the physical interpretation for most of the Hamiltonians, e.g. the polynomial constants keep track of the regularity and extremality of the solutions etc..
- ▶ We anticipate to investigate the Hamilt. in more involved models, such as the STU model.
- ▶ We believe that the  $n$  Hamilt. will provide a complete set of commuting observables for the quantum description of BH.

# Conclusion and Outlook

- ▶ We have established new insights into the solvability and integrability of the geodesic eqs following from reducing symmetric supergravities over the timelike direction.
- ▶ We have presented a recursive but closed formula for the coset representative describing a generic geodesic solution.
- ▶ Our results solve an open-standing question about the existence of a fake superpotential (Hamilton-Jacobi) for black hole solutions.
- ▶ Since Liouville Integrability implies HJ integrability we have proven the (local) **existence** of a fake superpotential for all stationary and spherically symmetric BH's.
- ▶ We have given the physical interpretation for most of the Hamiltonians, e.g. the polynomial constants keep track of the regularity and extremality of the solutions etc..
- ▶ We anticipate to investigate the Hamilt. in more involved models, such as the STU model.
- ▶ We believe that the  $n$  Hamilt. will provide a complete set of commuting observables for the quantum description of BH.

# Conclusion and Outlook

- ▶ We have established new insights into the solvability and integrability of the geodesic eqs following from reducing symmetric supergravities over the timelike direction.
- ▶ We have presented a recursive but closed formula for the coset representative describing a generic geodesic solution.
- ▶ Our results solve an open-standing question about the existence of a fake superpotential (Hamilton-Jacobi) for black hole solutions.
- ▶ Since Liouville Integrability implies HJ integrability we have proven the (local) **existence** of a fake superpotential for all stationary and spherically symmetric BH's.
- ▶ We have given the physical interpretation for most of the Hamiltonians, e.g. the polynomial constants keep track of the regularity and extremality of the solutions etc..
- ▶ We anticipate to investigate the Hamilt. in more involved models, such as the STU model.
- ▶ We believe that the  $n$  Hamilt. will provide a complete set of commuting observables for the quantum description of BH.

# Conclusion and Outlook

- ▶ We have established new insights into the solvability and integrability of the geodesic eqs following from reducing symmetric supergravities over the timelike direction.
- ▶ We have presented a recursive but closed formula for the coset representative describing a generic geodesic solution.
- ▶ Our results solve an open-standing question about the existence of a fake superpotential (Hamilton-Jacobi) for black hole solutions.
- ▶ Since Liouville Integrability implies HJ integrability we have proven the (local) **existence** of a fake superpotential for all stationary and spherically symmetric BH's.
- ▶ We have given the physical interpretation for most of the Hamiltonians, e.g. the polynomial constants keep track of the regularity and extremality of the solutions etc..
- ▶ We anticipate to investigate the Hamilt. in more involved models, such as the STU model.
- ▶ We believe that the  $n$  Hamilt. will provide a complete set of commuting observables for the quantum description of BH.

# Conclusion and Outlook

- ▶ We have established new insights into the solvability and integrability of the geodesic eqs following from reducing symmetric supergravities over the timelike direction.
- ▶ We have presented a recursive but closed formula for the coset representative describing a generic geodesic solution.
- ▶ Our results solve an open-standing question about the existence of a fake superpotential (Hamilton-Jacobi) for black hole solutions.
- ▶ Since Liouville Integrability implies HJ integrability we have proven the (local) **existence** of a fake superpotential for all stationary and spherically symmetric BH's.
- ▶ We have given the physical interpretation for most of the Hamiltonians, e.g. the polynomial constants keep track of the regularity and extremality of the solutions etc..
- ▶ We anticipate to investigate the Hamilt. in more involved models, such as the STU model.
- ▶ We believe that the  $n$  Hamilt. will provide a complete set of commuting observables for the quantum description of BH.